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PRODUCT CATALOG

480-1309Y-EU-R0

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Features of DC Brushless Motor

High torque	
	DCI
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	load

Energy saving	
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	saving
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Dynamic brake	
	DC b
	Dyna This
	slips
	brake
	case
	0400
Wide speed range	
	DC b
	SEN
	provi
	adjus
Functionality and Logic control	
U	Our d
	Dyna
	Snee

etc.

brushless motor provides much higher torque compare he same size AC motor which enables to handle heavier with minimum number of Motor Rollers.

orushless motor is known as more efficient at verting electricity into mechanical power than entional AC induction motor.

Motor Roller conveyor line is typically sub-divided into nes" and each zone is powered and controlled pendently only when a tote is present (Run On and).

Run On Demand feature provides further energy ng by more than 50% compared to the conventional conveyor.

orushless motor provides electrical brake method called amic brake or Regenerative brake.

feature provides instantaneous stop unless the product over the tube surface, thus there are no mechanical e device or pneumatic cylinder are required for many es.

brushless motor provides wide speed range (e.g. ERGY, Speed code 35 – Eco mode, diameter 50.0 mm ides from 5.0 to 49.8 m/min) and speed can be easily sted by Control card setting.

cutting-edge controls provide useful functions, not only amic brake or Variable speed, but such as Constant Speed control (Maintaining running speed regardless of load conditions), Acceleration & Deceleration timer setting,

Also ConveyLinx provides system-control-like functions such as ZPA (Zero Pressure Accumulation) which can minimise wirings and PLC programing.

PULSE ROLLER Drives Overview

SENERGY-Ai



Product type	Motor Roller
Rated voltage	DC24V
Output	50W (Max)
Conveyor speed	2.0 ~ 304.1 m/min (50.0 mm diameter)

PGD-Ai



	Product type	Geared Drive
	Rated voltage	DC24V
ð	Output	50W (Max)
	Rotational speed	8.5 ~ 528.9 rpm (Output shaft)

SENERGY-Ai

Introduction

Ai (Advanced intelligence) technology incorporates a small micro controller on the hall effect sensor board of the Senergy Ai motor and achieved to eliminate the need to have the commutation electronics inside the motor roller. The micro controller codes the hall effect signals to only one pin, allowing the connection with a standard M8-4pin connector for proven and fail-safe connection.

The micro controller also holds, roller serial number, roller diameter, gear ratio, manufacturing date and measures the real-time motor temperature. This allows in-depth analysis of the motor roller in operation. Ai technology is a brilliant piece of ingenuity in motorized rollers.

ECO and BOOST mode are two performance mode of Senergy Ai. In ECO mode the continuous performance is 40W, and 50W in BOOST mode. ECO mode is sufficient for most typical zoned conveyor applications. BOOST mode should be used for higher loads, belted zones or motion control application.

Both performance modes can be easily selected by our Control cards.

Product information

General information

-Tube material:	Mild steel, zinc plating / Stainless steel (SUS304)				
-Roller diameter:	48.6, 50.0, 57.0, 60.5 (mm)				
-Min. roller length:	Refer to the "Minimum available roller length table" below.				
-Max. roller length:	1000 mm *Contact us for longer than 1000 mm.				
-Connector:	4-pin M8 connector cabling				
-Cable length:	1000 mm				
-Advanced intelliger	nce inside:				
	Internal diagnostics (Real time motor temp report)				
	Product information stored (Serial number, Date of				
	Manufacturing, Gear ratio, Roller diameter, etc)				
-Operation:	0.5 sec ON / 0.5 sec OFF duty cycle (Minimum)				

or continuous within rated load



Technical data

	Eco-mode Boost-mode				
Voltage	DC24V				
Nominal output	40W	50W			
Rated current	2.5A	3.5A			
Starting current	3.0A	5.0A			
Ambient temperature	-10 ~ 40°C				
Ambient humidity	10 ~ 90% RH (No condensation)				

Available minimum roller length

Roller diameter		Interlocking option					
	Speed Code	Plain straight	Micro V-Pulley	Round Groove	Sprocket		
	15, 20, 25	324	317	356	329		
48.6 / 50.0	6 / 50.0 35, 45, 60, 75		96 289 32		301		
	95, 125, 175, 215	273	266	305	278		
	15, 20, 25	309	N/A	329	301		
57.0 / 60.5	35, 45, 60, 75	282	N/A	302	274		
	95, 125, 175, 215	258	N/A	278	250		
	1	I			Unit: mn		

*We support even shorter length than those listed above using specially made components. Contact us for more details.



Weight table

Diamatan	Created and a	Roller length							
Diameter	Speed code	300	400	500	600	700	800	900	1000
	15, 20, 25	2.0	2.1	2.3	2.5	2.6	2.8	2.9	3.1
φ48.6	35, 45, 60, 75	1.8	2.0	2.1	2.3	2.4	2.6	2.7	2.9
	95, 125, 175, 215	1.7	1.8	2.0	2.1	2.3	2.5	2.6	2.8
	15, 20, 25	2.0	2.2	2.4	2.5	2.7	2.9	3.0	3.2
φ50	35, 45, 60, 75	1.8	2.0	2.2	2.4	2.5	2.7	2.9	3.0
	95, 125, 175, 215	1.7	1.9	2.0	2.2	2.4	2.6	2.7	2.9
	15, 20, 25	2.4	2.6	2.8	3.0	3.2	3.4	3.6	3.8
φ57	35, 45, 60, 75	2.2	2.4	2.6	2.8	3.0	3.2	3.4	3.6
	95, 125, 175, 215	2.1	2.3	2.5	2.7	2.8	3.0	3.2	3.4
	15, 20, 25	3.1	3.6	4.0	4.5	4.9	5.3	5.8	6.2
φ60.5	35, 45, 60, 75	2.9	3.4	3.8	4.3	4.7	5.2	5.6	6.1
	95, 125, 175, 215	2.8	3.2	3.7	4.1	4.6	5.0	5.5	5.9

Wall thickness

Diameter	48.6	50.0	57.0	6
Thickness	1.4	1.5	1.5	3

Static load capacity

Length	300	400	500	600	700	800	900	1000
48.6	70	60	50	40	35	30	25	20
50.0	80	70	60	55	50	45	40	35
57.0	100	100	80	80	60	60	50	50
60.5	160	160	130	130	100	100	80	80
								LL-26 Los



	/	
art		1

*Weight varies depending on interlocking options. Unit: kg

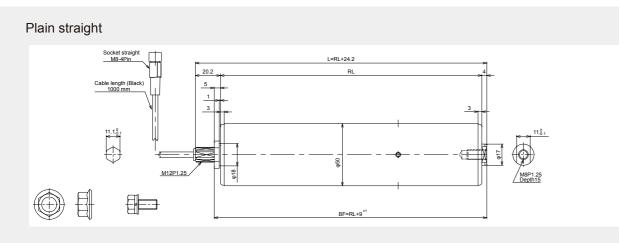
60.5

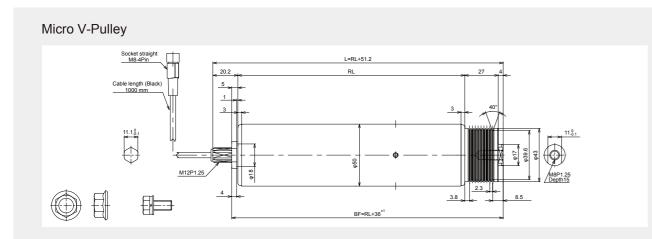
3.25

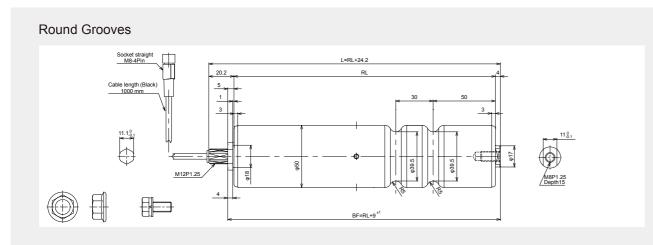
Unit: mm

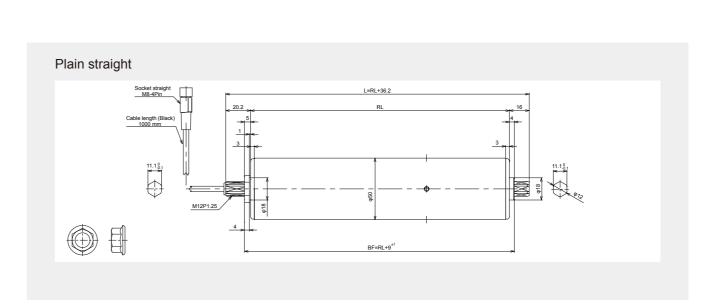
Unit: kg

Dimensions (Reference drawing)









Micro V-Pulley

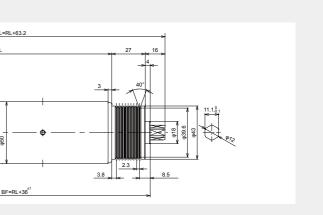
Round Grooves

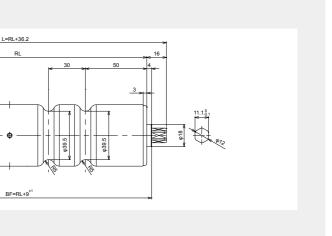




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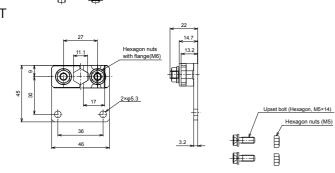
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Bracket (for Non-threaded cable end shaft)

Standard accessory

(Cable side)

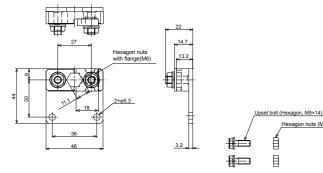
PR-D-30H-PU-N-ST (Point-up)



SHE SHE

Note
 Tightening torque (M6): 8 ~ 10 N-m
 Tightening torque (M5): 2.3 ~ 3.5 N-m

PR-D-30H-FU-N-ST (Flat-up)

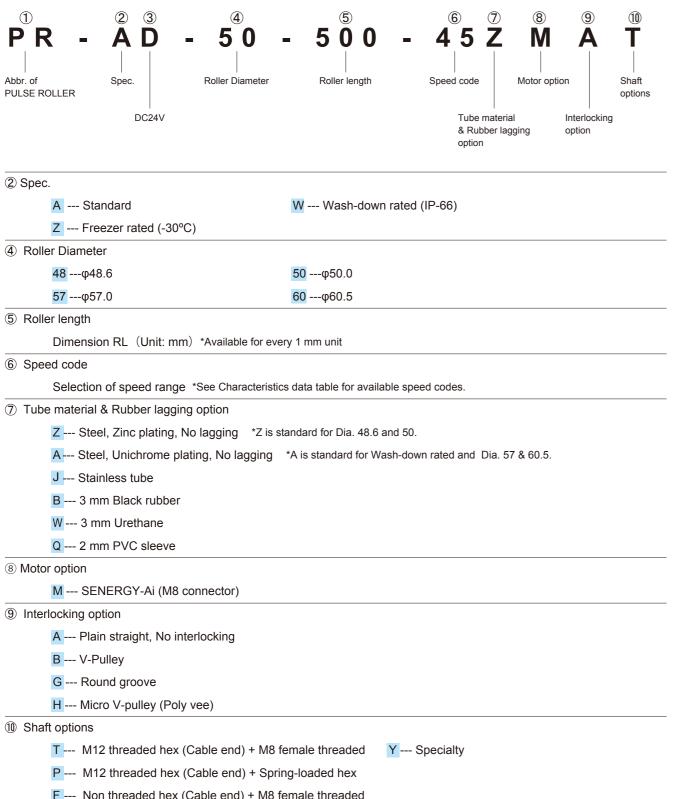


 Note Tightening torque (M6) : 8 ~ 10 N-m Tightening torque (M5) : 2.3 ~ 3.5 N-m









F --- Non threaded hex (Cable end) + M8 female threaded

Q --- Non threaded hex (Cable end) + Spring-loaded hex

10



Characteristics data

Roller Dia: 50.0 mm

Spood				E	CO-mo	de						BC	OST-m	node							
Speed	Gearbox	Speed	Тс	orque(N-	m)	Tangentia	al force(N)	Curre	ent (A)	Speed	То	rque(N-	m)	Tangentia	al force(N)	Curre	nt (A)				
Code		(m/min)	Rated	Starting	Accel	Rated	Starting	Rated (max)	Starting	(m/min)	Rated	Starting	Accel	Rated	Starting	Rated (max)	Starting				
15		2.0 ~ 20.3	2.97	16.39	4.95	118.8	655.7			2.0 ~ 14.7	5.40	21.37	7.94	216.0	855.0						
20	3 stage	2.7 ~ 27.7	2.17	12.00	3.62	86.9	480.0			2.7 ~ 20.0	3.95	15.64	5.81	158.1	625.8						
25		3.4 ~ 33.8	1.78	9.83	2.97	71.2	393.4			3.4 ~ 24.4	3.24	12.82	4.76	129.6	513.0						
35		4.9 ~ 49.9 1.20 6.66 2.00 48.3 266.6			4.9 ~ 36.1	2.19	8.69	3.59	87.8	347.7											
45	2 stage	6.0 ~ 60.8	0.99	5.46	1.65	39.6	218.5	2.5	3.0	6.0 ~ 44.0	1.80	7.12	2.94	72.0	285.0						
60	2 Slage	8.2 ~ 83.1	0.72	4.00	1.20	28.9	160.0			8.2 ~ 60.1	1.31	5.21	2.15	52.7	208.6	3.5	5.0				
75		10.1 ~ 101.4	0.59	3.27	0.98	23.7	131.1							10.1 ~ 73.3	1.08	4.27	1.76	43.2	171.0		
95		13.3 ~ 133.8	0.44	2.48	0.73	17.9	99.3			13.3 ~ 96.8	0.81	3.23	1.49	32.7	129.5						
125	- 1 stage	18.1 ~ 182.5	0.33	1.82	0.55	13.2	72.8			18.1 ~ 131.9	0.60	2.37	1.09	24.0	95.0						
175		24.7 ~ 249.3	0.24	1.33	0.40	9.6	53.3			24.7 ~ 180.3	0.43	1.73	0.78	17.5	69.5						
215		30.2 ~ 304.1	0.19	1.09	0.32	7.9	43.7			30.2 ~ 219.9	0.36	1.42	0.65	14.4	57.0						

Senergy Ai torque values are tested data and shall help to apply the product in a right way.

- Rated torque

This torque value can be delivered by Senergy Ai for continuous use without overheating in environmental temperature of 25°C. Average torque of start/stop operation should not exceed this torque value.

- Starting torque :

This torque is the peak value of motor stall torque.

- Accel torque :

This torque is the average torque which is present in the phase of acceleration up to set speed. This torque value can be used to calculate real acceleration time of an application. However torque consumption of idler rollers and belts also must be taken into consideration.

NOTE : When the motor is warmed up, torque performance will be less than above values, therefore enough safety factor consideration is necessary to pick the right speed code for each application.



Wash-down rated

-IP rating:	IP-66
-Material:	All stainless made (Pipe: SUS304, Side plate and shaft: SUS303)
-Roller diameter:	48.6, 50.0, 57.0, 60.5 (mm)
-Min. roller length:	Refer to the "Available minimum roller length" table below.
-Max. roller length:	1000 mm *Contact us for longer than 1000 mm.
-Cable length:	1000 mm



* Controls are not Wash-down rated.

Optional spec.

Freezer rated

-Applicable Temp:	From 0 down to -30°C (No condensation)
-Tube material:	Mild steel, zinc plating / Stainless steel (SUS
-Side plate material:	Aluminium
-Roller diameter:	48.6, 50.0, 57.0, 60.5 (mm)
-Min. roller length:	Same as standard model
-Max. roller length:	1000 mm *Contact us for longer than 1000 mm.
-Cable length:	1000 mm

Part numbers example

W for Wash-down

PR - WD - 50 - 500 - 45 A MAT Tube material & Rubber lagging option Spec.

A is standard for Wash-down rated.

Available minimum roller length

		Interlocking option							
Roller diameter	Speed Code	Plain straight	Micro V-Pulley	V-Pulley	Round Groove				
	15, 20, 25	360	344	351	381				
48.6 / 50.0	35, 45, 60, 75	332	317	324	354				
	95, 125, 175, 215	309	294	301	330				
	15, 20, 25	347	N/A	341	347				
57.0 / 60.5	35, 45, 60, 75	320	N/A	314	320				
	95, 125, 175, 215	296	N/A	290	296				

*We support even shorter length than those listed above using specially made components. Contact us for more details.

Unit: mm

Part numbers example

PR - ZD - 50 - 500 - 45ZMAT Spec. Z for Freezer rated



S304)

Compatible Control Technologies Ē



* For freezer application, above controls need to be specially made. Please contact us for more details.



PGD-Ai -Pulse Geared Drive-

Product information

General information

-Mounting: M5 x 7mm -Shaft diameter: 16 mm 5 x 5 x 25 mm -Key: -Cable length: 1000 mm

Compatible Control Technologies Ø COD CONVEYLINX EQUBE

Characteristics data

Nominal	Actual				ECO	-mode					BOOS	T-mode						
Gear ratio		Gear box	Sp	beed	т	orque(N-n	n)	Curre	ent (A)	Speed	т	orque(N-n	n)	Curre	ent (A)			
Geal Tallo	Gear Tallo	DOX	(r	pm)	Rated	Starting	Accel	Rated (max)	Starting	(rpm)	Rated	Starting	Accel	Rated (max)	Starting			
67	67.222•••		8.5	~ 86.7	4.40	24.4	7.33						8.5 ~ 62.7	8.03	31.81	11.82		
45	45.00	3	12.8	~ 129.0	2.97	16.39	4.95			12.8 ~ 93.3	5.40	21.37	7.94					
33	32.999•••	stage	17.4	~ 176.3	2.17	12.00	3.62			17.4 ~ 127.5	3.95	15.64	5.81					
27	27.00		21.3	~ 215.1	1.78	9.83	2.97	2.5	3.0	21.3 ~ 155.5	3.24	12.82	4.76	3.5	5.0			
18	18.333•••		31.4	~ 317.3	1.20	6.66	2.00	2.5	5.0	31.4 ~ 229.5	2.19	8.69	3.59	3.5	5.0			
15	15.00	2	38.4	~ 387.2	0.99	5.46	1.65			38.4 ~ 280.0	1.80	7.12	2.94					
11	10.999•••	stage	52.4	~ 528.9	0.72	4.00	1.20			52.4 ~ 382.5	1.31	5.21	2.15					
9	9.00		64.0	~ 645.3	0.59	3.27	0.98	1		64.0 ~ 466.6	1.08	4.27	1.76	1				

Technical data

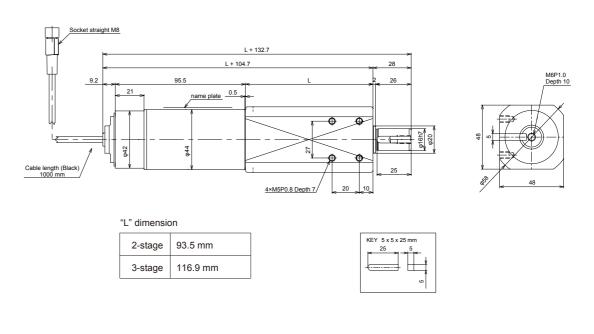
	Eco-mode	Boost-mode
Voltage	DC	24V
Nominal output	40W	50W
Rated current	2.5A	3.5A
Starting current	3.0A	5.0A
Ambient temperature	-10 ~	40°C
Ambient humidity	10~90% RH (N	o condensation)

Weight table

Gear box	Reduction ratio	Weight
3 stage	67, 45, 33, 27	1.5
2 stage	18, 15, 11, 9	1.2

Unit: kg

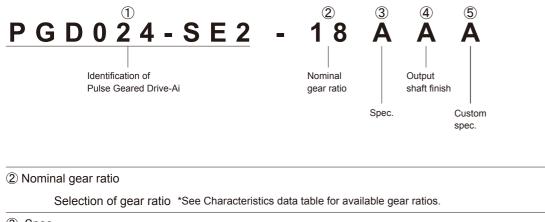
Dimensions (Metric)





PGD-Ai -Pulse Geared Drive-

Part numbers example



③ Spec.

A --- Standard

④ Output shaft finish

A --- Standard key-way shaft (No attachment)

(5) Custom spec.

A --- Standard

Y --- Others



Control EQUBE

Features

- Part number : EQube-Ai-P
- M8 4 pin connector for Motor
- ECO mode performance only
- LED Indicator for Power, Run, Reverse and Error
- 32 fixed speed setting by DIP Switch setting
- 3 stage speed selection via signal input
- Bi-directional operation
- Dynamic brake
- PI regulator (stable speed control)
- 16 stage Accel / Decel timer for 0 2.5 sec by DIP Switch setting
- Only PNP input applicable

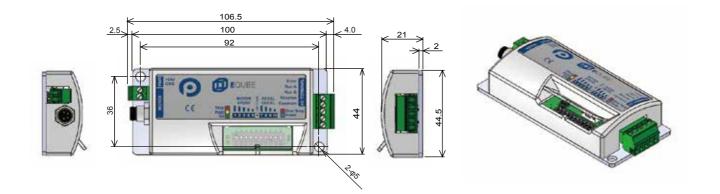
Technical data

Voltage	DC24V
Voltage range	18 ~ 28V
Rated current	2.5A
Starting current	3.0A
Fuse	Present

Applicable environment

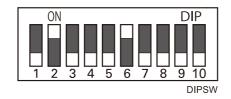
Operating ambient temp	-10 ~ 80°C
Operating ambient humidity	10 ~ 90% RH (Non condensation)
Storage ambient temp	-10 ~ 75°C
Storage ambient humidity	10 ~ 90% RH (Non condensation)
Vibration	2G or less

Dimensions and parts



Small & Simple Control Card

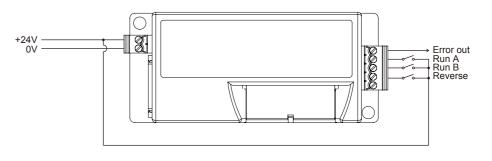
DIP Switch Speed and Acceleration / Deceleration Setting



*Above setting is for illustrative only

No.	Function	
1		
2		
3	Speed setting	32 fixed sta
4		
5		
6	Direction of rotation	ON = CCW
7		
8	Acceleration / Deceleration	16 fixed tim
9	timer setting	
10		

Wiring



Speed setting via signal input

Run A	100% of set speed by DIP switch
Run A + B	75% of set speed by DIP switch
Run B	50% of set speed by DIP switch



Description

ages available by DIP switch combinations

, OFF = CW

ner (0 ~ 2.5 sec) available by DIP switch combinations

Control

CONVEYLINX

Features

- Part number : ConveyLinx-Ai2 (for Senergy-Ai roller and PGD-Ai)
- M8 4 pin connector for Motors and Sensors
- PROFINET Ethernet I/P, Modbus/TCP, Connectivity
- 2 Zones control (Up to 4 sensors and 2 motors connections)
- Baud rate: 10Mbps / 100Mbps
- Both NPN/PNP photo-eye sensor applicable
- ZPA (Zero Pressure Accumulation) logic; Singulation, Train and Gap Train
- EasyRoll Software for changing default configuration and customizing functionality of each module
- Auto configuration for quick set-up (from EasyRoll software)
- Motor error detection (Overload, Over-current, motor not connected)
- Jam error detection (Sensor Jam, Arrival Jam)
- -Separate power for Motor and Logic

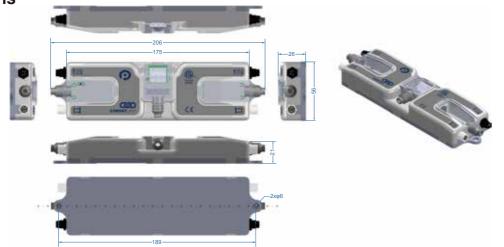
Technical data

Voltage	DC24V
Voltage range	18 ~ 28V
Rated current	5.0A (Eco), 7.0A (Boost) *Two Motors
Starting current	6.0A (Eco), 10.0A (Boost) *Two Motors
Fuse	Present

Applicable environment

Operating ambient temp	0 ~ 40°C
Operating ambient humidity	10 ~ 90% RH (Non condensation)
Storage ambient temp	-10 ~ 75°C
Storage ambient humidity	10 ~ 90% RH (Non condensation)
Vibration	2G or less

Dimensions



Networked, Built-in ZPA (Zero Pressure Accumulation) Controller

EasyRoll Configuration Software

EstyRoll Version 40 (EUROPE) Current IP: 192.168.22.27	
From Node 8 0 To Node 8 0 2 Set Al	Cose Design
Let Link C C Right Link	• • • • • • • • • • • • • • • • • • •
Updream Zone	Downsteam Zone
ZPA Mode: Singulation + Set41 Dear Jan Env. 0	ZPA Mode: Singulation · Set48 Close Jan Ever @
3 GAP Taves 0.00 sec 3/	GAP Tener 0.00 sec and JAM Encr Counter 0
T-cone 0.00 sec Set	T-gone 0.00 sec Set
Convert Trainers Tempeters Disable Server Jan Auto Dear Disable Anival Teneout Set Disable Anival Jan Reset Delay Disable Server Jan Reset Delay	Constant Transmission Constant Service Junit Auto Clear Constant Transmission Constant Constant Service Junit Activity Constant Service Constant Activity Activity Ac
Arival/Departure 0/0	Anval/Departure D/D
4 et MDB (5)	(4) Ride MDR (5)
E LEK MUM	Entr
Motor Type: Serenge Ai ECO Servital Service Connection Exoc	Motor Type: Senergy-ArECO + SetAl Sensor Connection Erson
Mator Type: Serverga Ai ECO Sevial Servor Correction Eroc Italia Method: Normal Secial Servor Gain Eroc	Motor Type: Senargy-ArECO SetAld Senarc Connection Ence Baske Method: Normal SetAld Senarc Can Ence
Motor Type: Serverge 4 ECO Server Convection Exer	Motor Type: Senergy-Ai ECO Set44 Senor Convection Enco
Motor Type: Severy-Air ECO Severy Correction Exect Italia Method: Normal Severy Correction Exec Severy Severy Seve	Motor Type, SeresguérECO Setal Senso Correction Enc. Baska Method Inomal Setal Setal Senso Gain Enc. Add Speed 0.00 m/s Saeed 0.51 m/s Set Setal
Motor Type: Serverg-Air ECD Server Correction Exer Inside Method: Normal Server Server Gain Exer Read Speed: 0.00 m/s Speed: 0.51 m/s Set SetAl Motor Corrector Exer	Motor Type, Sereszy-ArECO Setal Senso Connection Exoc Setal Senso Connection Exoc Setal Senso Can Exoc Setal Senso Can Exoc Setal Senso Can Exoc Setal Senso Can Exoc Setal Senso Can Exoc Setal Senso Can Exoc Setal Setal Senso Can Exoc Setal Setal Setal Motor Connector Exoc Setal
Motor Type: Server Correction Even Italia: Method: Nonal Server Correction Even Italia: Method: Nonal Server Correction Even Read Speed: 0.00 sv/t Server Gain Ein Courter Speed: 0.51 sv/t Server Gain Ein Courter CW/CCW: Cwire: Server Server Gain Ein Courter	Motor Type, Serengy-ALECO Setal Sensor Convection Enor. Setal Sensor Gain Enor. Setal Sensor Gain Enor. Setal Sensor Gain Enor. Setal Sensor Gain Enor. Setal Gain Enor.
Motor Type: Server Correction Exc. Italia Method Nonal - Server Correction Exc. Italia Method Nonal - Server Correction Exc. Read Speed 0.08 n/s Server Gain Exc. Speed 0.09 n/s Server Gain Exc. CW/CDW CW Server Gain Exc. Motor Connector Exc. Acceleration: 30 em. Server Gain Exc. Motor Connector Exc. Motor Connector Exc. Server Gain Exc. Over count. Over count.	Motor Type, Serengy-ALECO Settal Serios Connection Enor. Settal Serios Connection Enor. Settal Serios Connection Enor. Serios Gain En Curret: Serios Gain Enor. Settal Serios Gain Enor. Settal
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Main screen

- 1. Network IP The Subnet of the particular ConveyLinx network to be connected.
- 2. Node No. A range of Nodes in which to be connected.
- 3. Upstream Zone / Downstream Zone -Selection of ZPA mode, GAP timer and T-bone accept timer settings, etc.
- 4. Left / Right MDR (Motor Roller) -Selections for changing performance mode, speed, braking method, Accel/Decel distance setting, etc as well as showing values of operation status.
- 5. Error Error indicators of Sensor connection, Motor connection, Over current, Overload, etc.

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Advanced dialog screen

- * Press F2 key to invoke the Advanced Dialog.
- 1. Setting of Look Ahead feature, JAM timer, Run After timer, etc.
- 2. Upgrade Upgrade of firmware version
- 3. Special Service Reset operating time, Clear Motor-short circuit error
- 4. Control Ports Control ports' configuration
- 5. Flex Zone Flex Zone feature setting
- 6. Sensors Sensor ports' configuration

Calculation of Motor Roller capability

Required tangential force

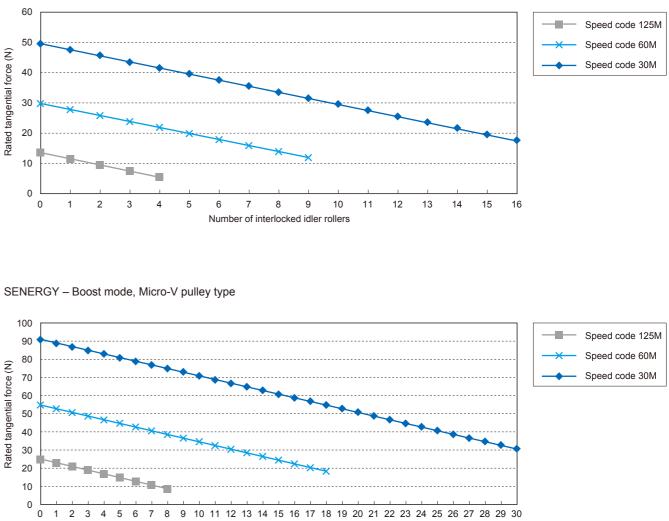
$F(N) = m \cdot g \cdot \mu$

- F = Required tangential force m = Mass (kg)
- g = Gravitational acceleration 9.8 m/s²
- μ = Coefficient of friction

Power loss when interlocking with idler rollers

This is very important factor when selecting a model for applications. As the table below shows that the capability (Tangential force) of PULSE ROLLER is lost when interlocking with idler rollers.

SENERGY - Eco mode, Micro-V pulley type



Coefficient of friction

Material	Wood	Steel	Cardboard	Plastic	Rubber
μ	0.02 ~ 0.05	0.01 ~ 0.02	0.05 ~ 0.1	0.02 ~ 0.04	0.1

---Example---

Weight of the product --- 50 kg Material of the product --- Cardboard (µ=0.1, maximum) Conveyor speed --- 40m/min

F = 50 x 9.8 x 0.1 = 49N

The model which can operate at 40m/min is; PR-AD-50-500-35ZSAA (SENERGY, Diameter: 50mm, Speed code35 - Eco mode) Starting tangential force: 274.3N

Since its tangential force exceeds the required tangential force (274.3 > 49), the selected model is considered to be capable to handle 50 kg cardboard.

*Note: please include adequate value of safety factor for the actual calculation of required tangential force. The required tangential force varies depending on various conditions.

